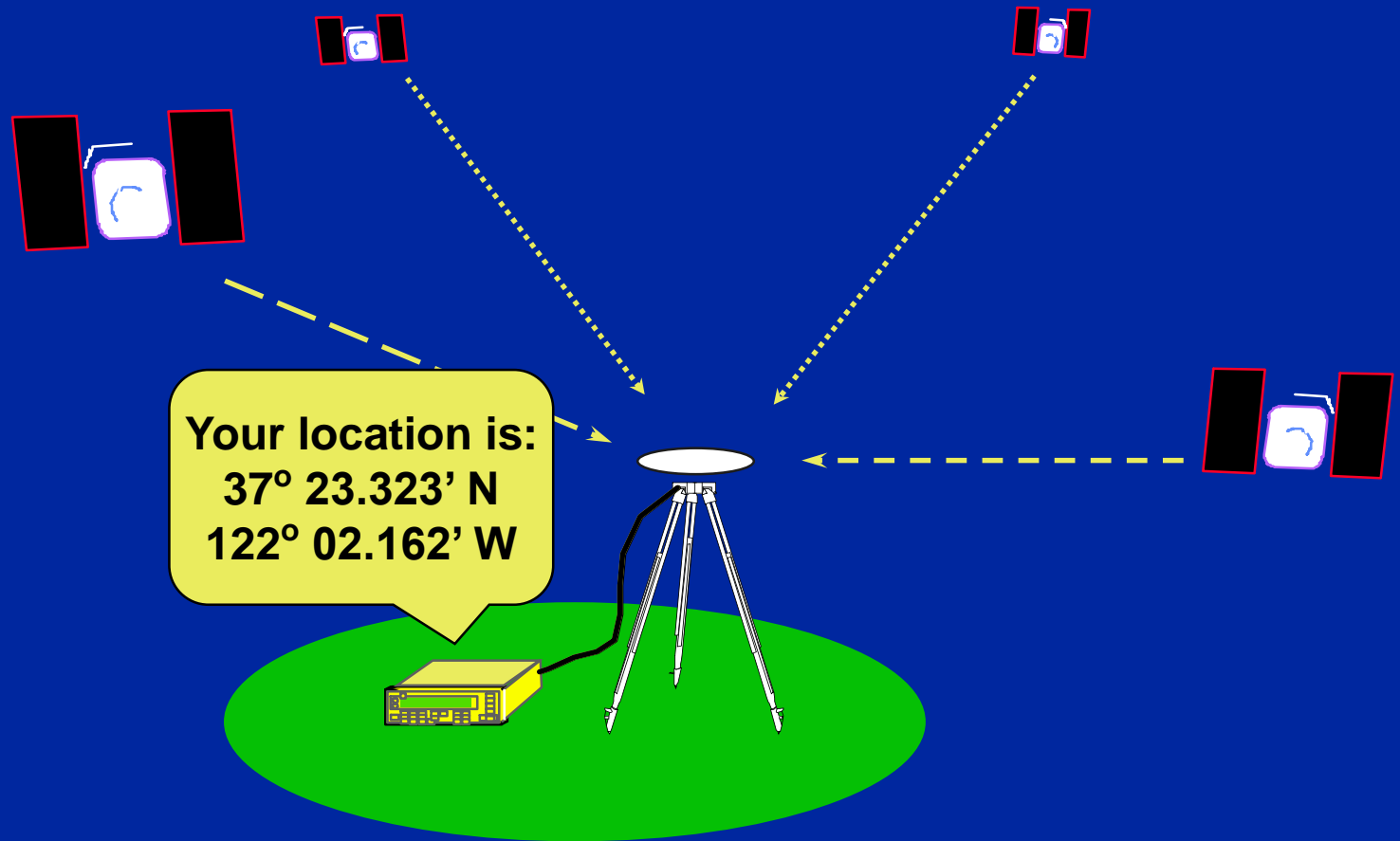
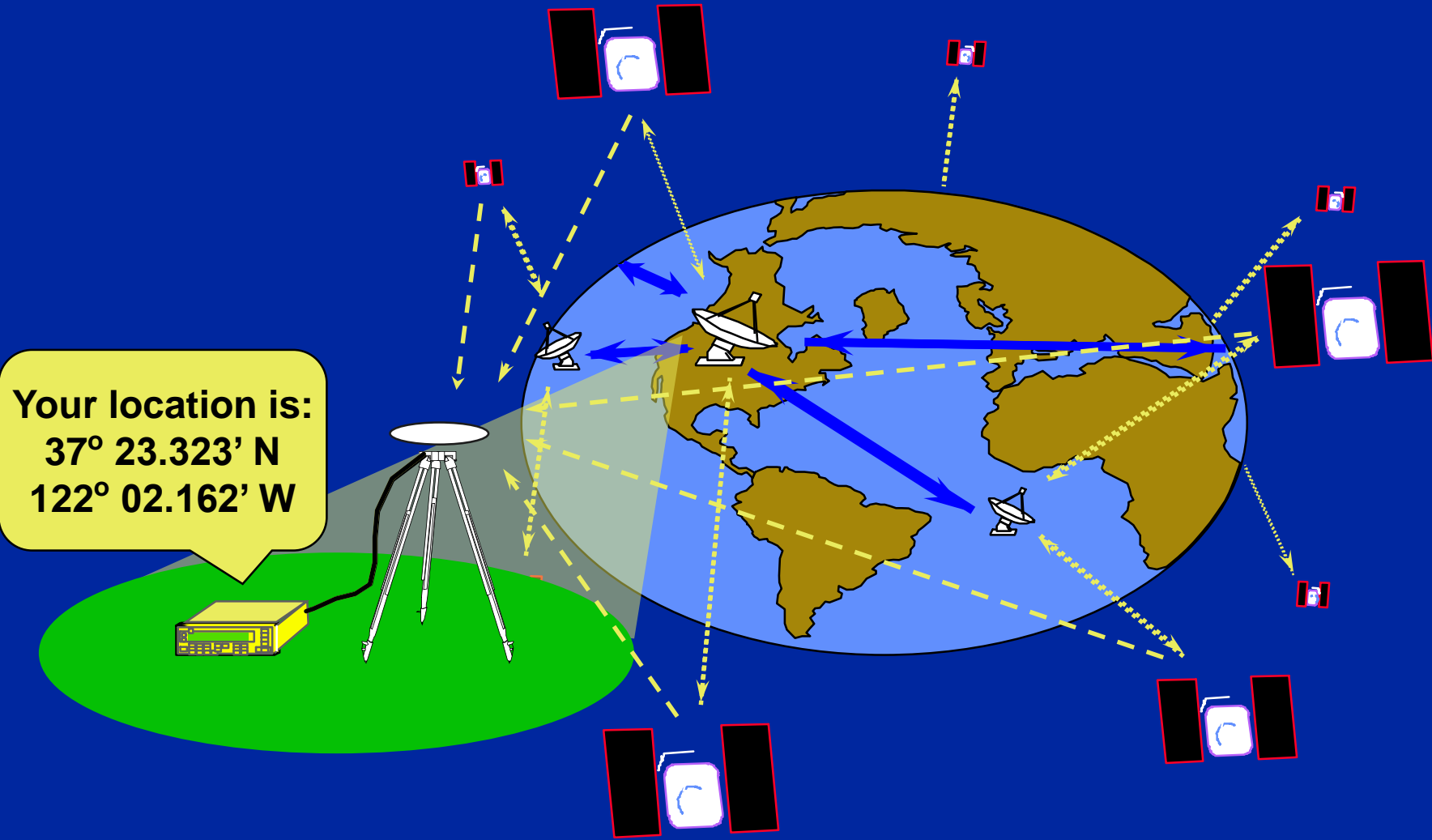
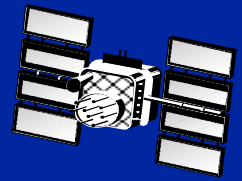


GPS Fundamentals

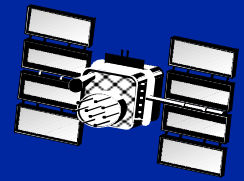


Global Positioning System



Your location is:
 $37^{\circ} 23.323' N$
 $122^{\circ} 02.162' W$

Satellite Signal Structure

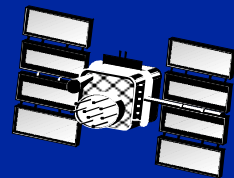


Carrier	L1	L2
Frequency	1575.42 MHz	1227.60 MHz
Wavelength	19cm	24cm
Code Modulation	C/A-code	-
	P(Y)-code	P(Y)-code
	NAVDATA	NAVDATA

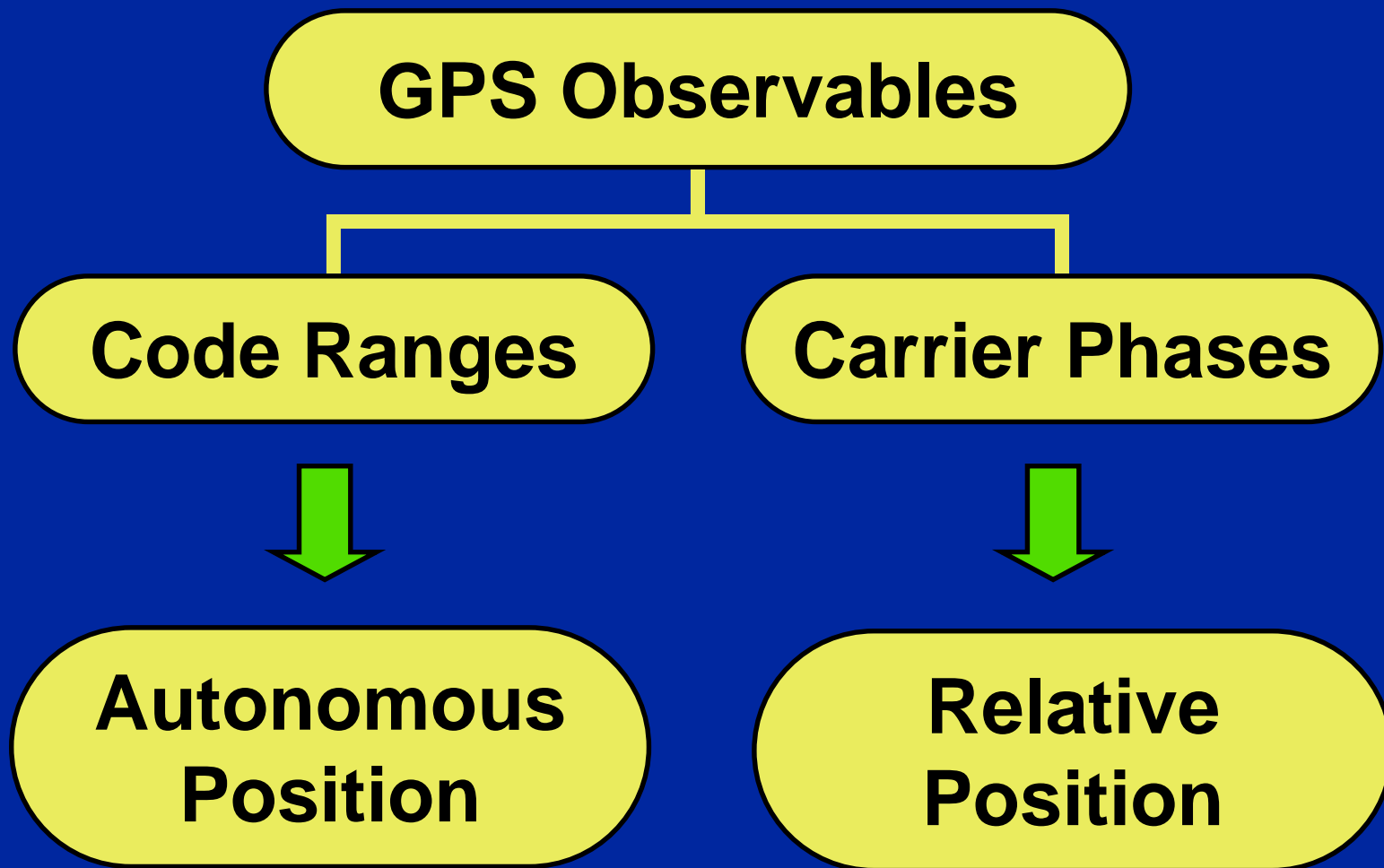
C/A - Coarse Acquisition Code

P - Precise Code (Y-Code when encrypted)

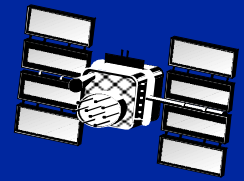
NAVDATA - Satellite health, satellite clock corrections, and ephemeris parameters.



What is Measured?



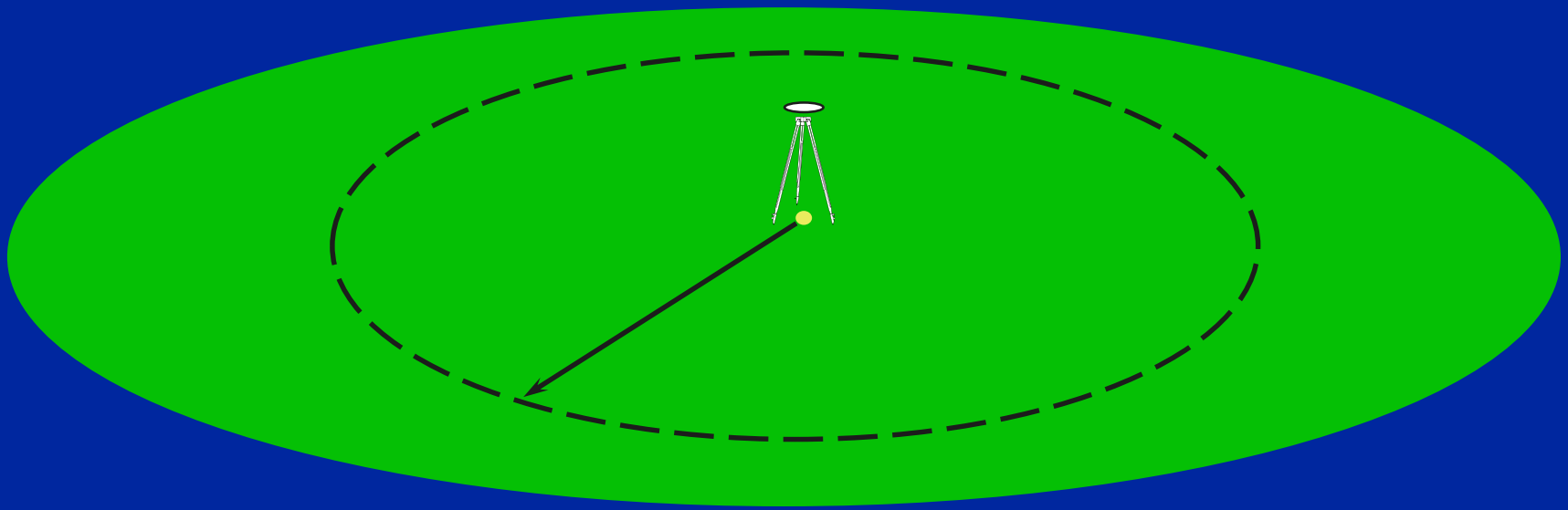
Code Range Results



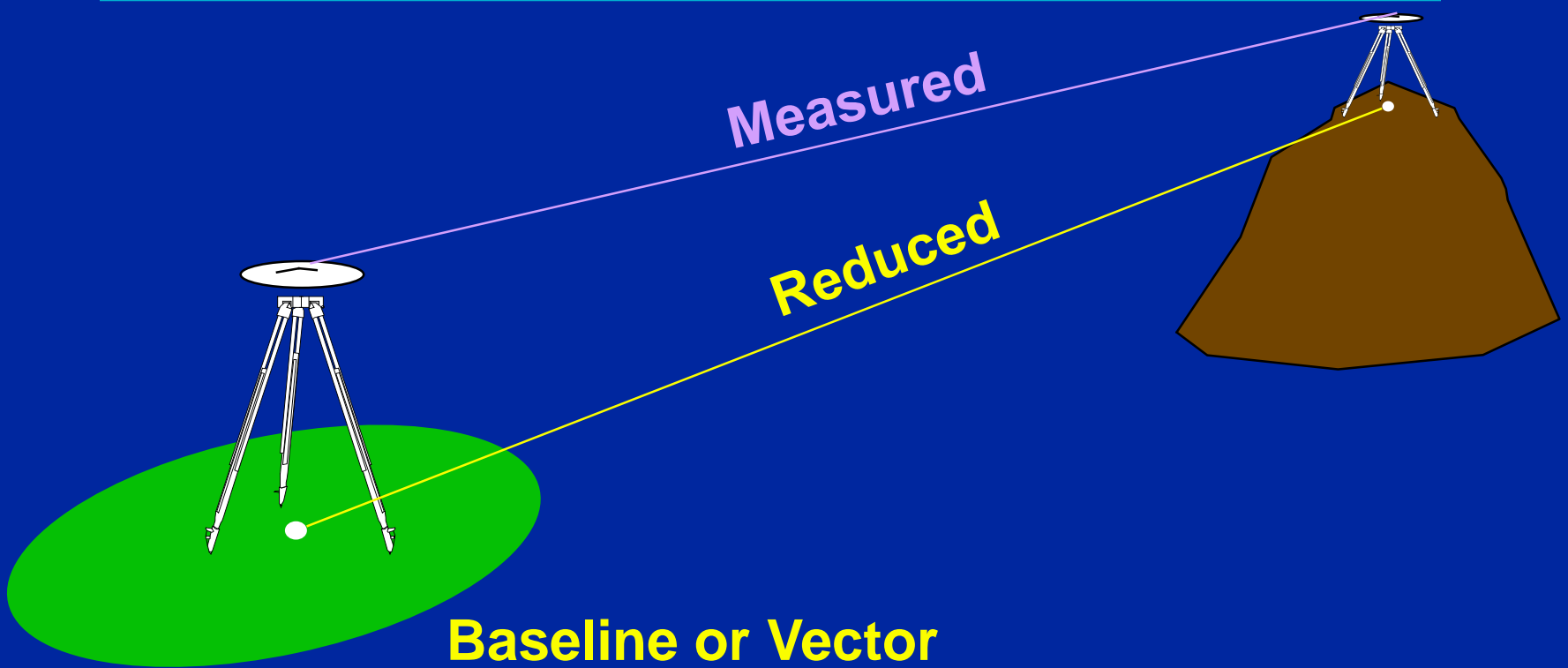
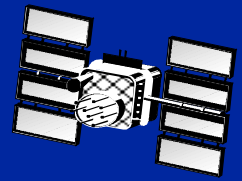
Autonomous Position

+/- 100 m (330 ft) error (horizontal)

+/- 156 m (515 ft) error (vertical)



Carrier Phase Results



**Baseline or Vector
(cm precision)**

Azi = 212° 42' 49.8244"

Dist = 557.05307 m

Δ Ell Ht = 4.8751 m

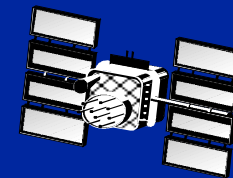
OR

Δ X = -408.251 m

Δ Y = -84.830 m

Δ Z = -369.413 m

ECEF Coordinate System

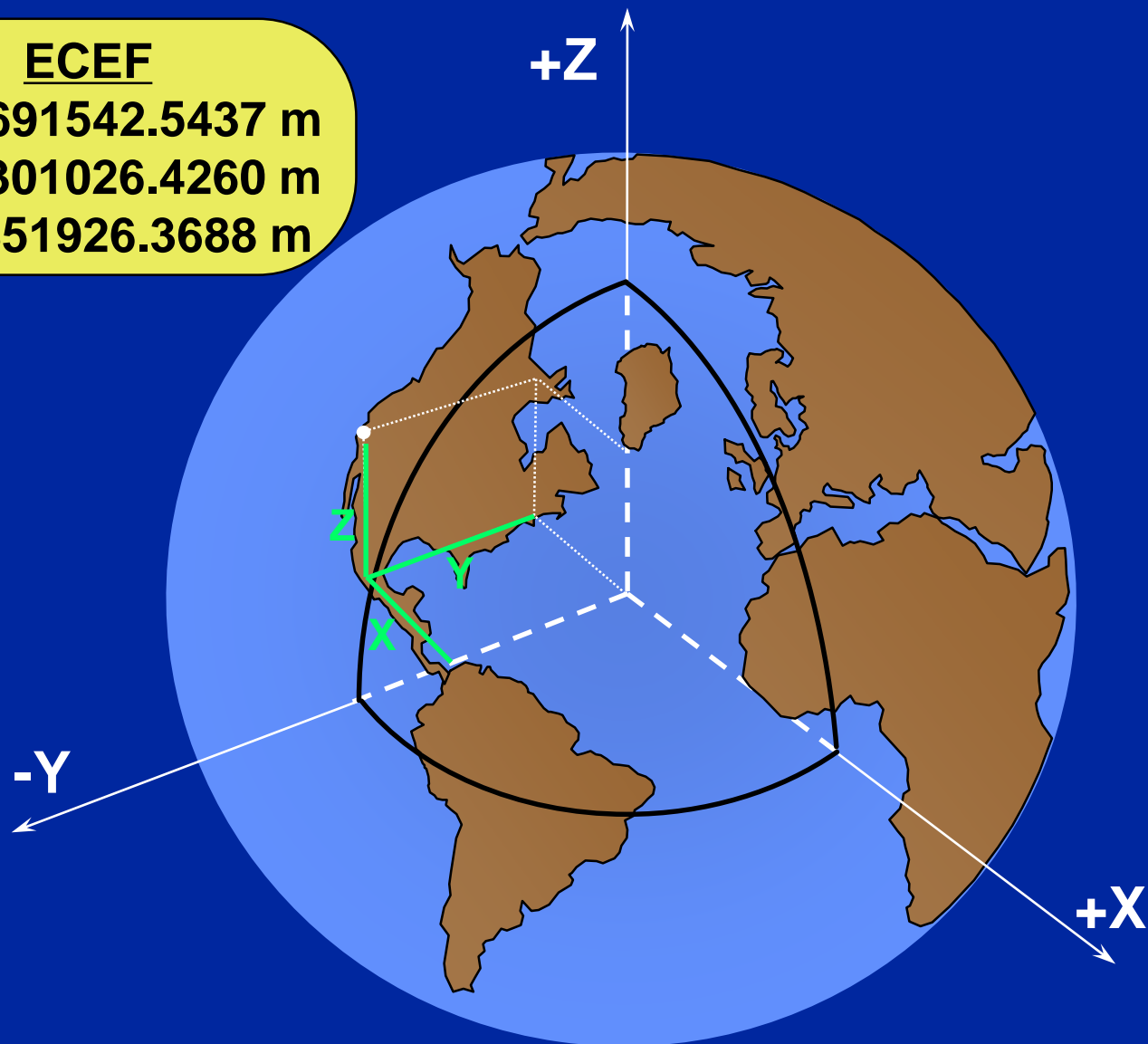


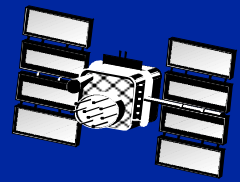
ECEF

$X = -2691542.5437 \text{ m}$

$Y = -4301026.4260 \text{ m}$

$Z = 3851926.3688 \text{ m}$





Reference Ellipsoid

a = semi-major axis

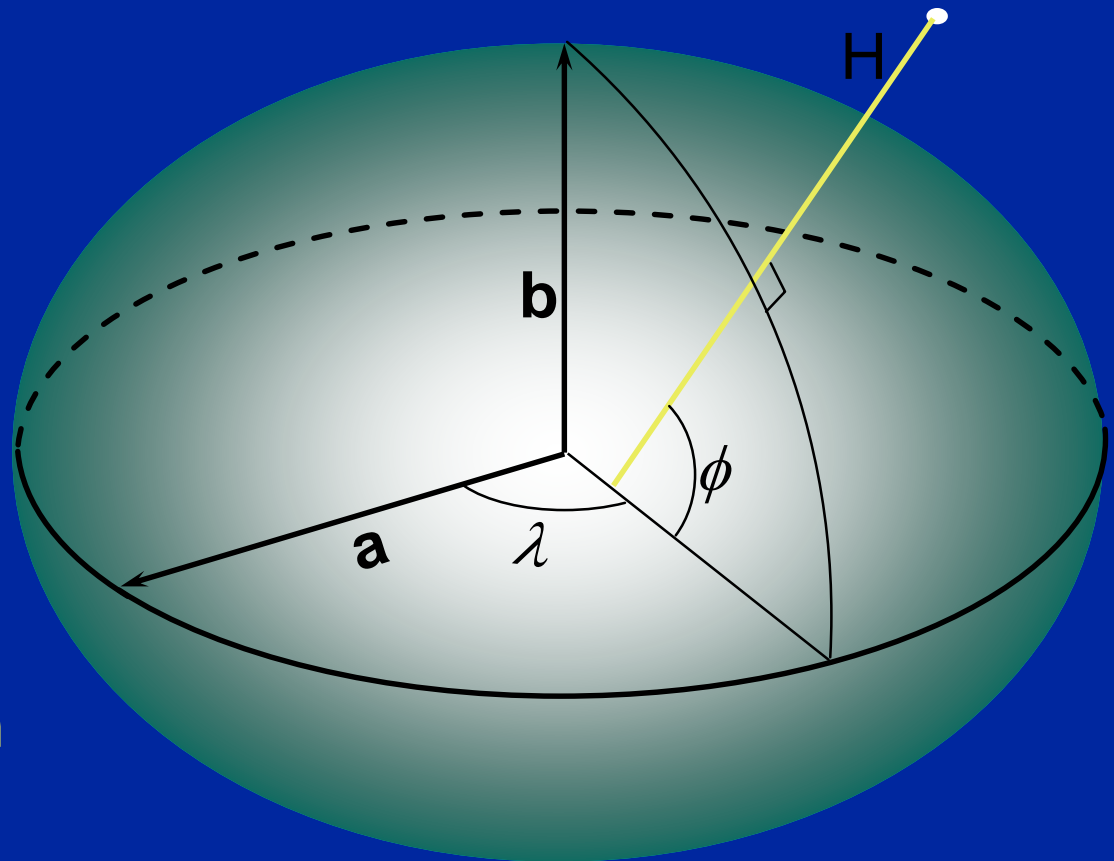
b = semi-minor axis

Flattening $f = \frac{(a-b)}{a}$

$\phi \equiv$ latitude

$\lambda \equiv$ longitude

$H \equiv$ ellipsoidal height



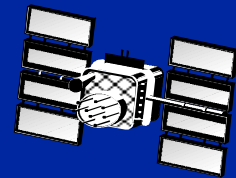
WGS-84 Ellipsoid

$a = 6378137.000000$ m

$b = 6356752.314245$ m

$1/f = 298.2572235630$

ECEF and WGS-84

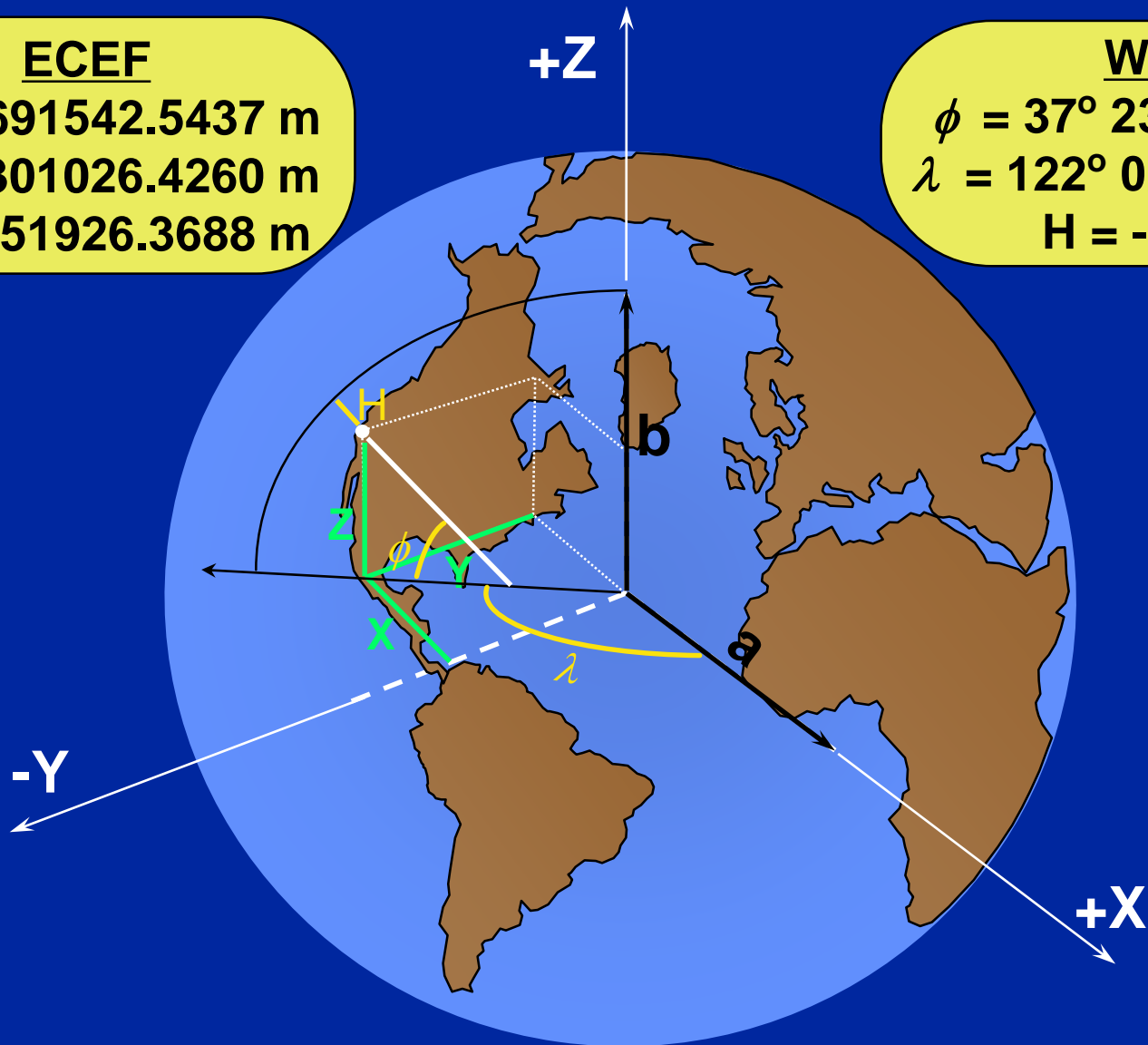


ECEF

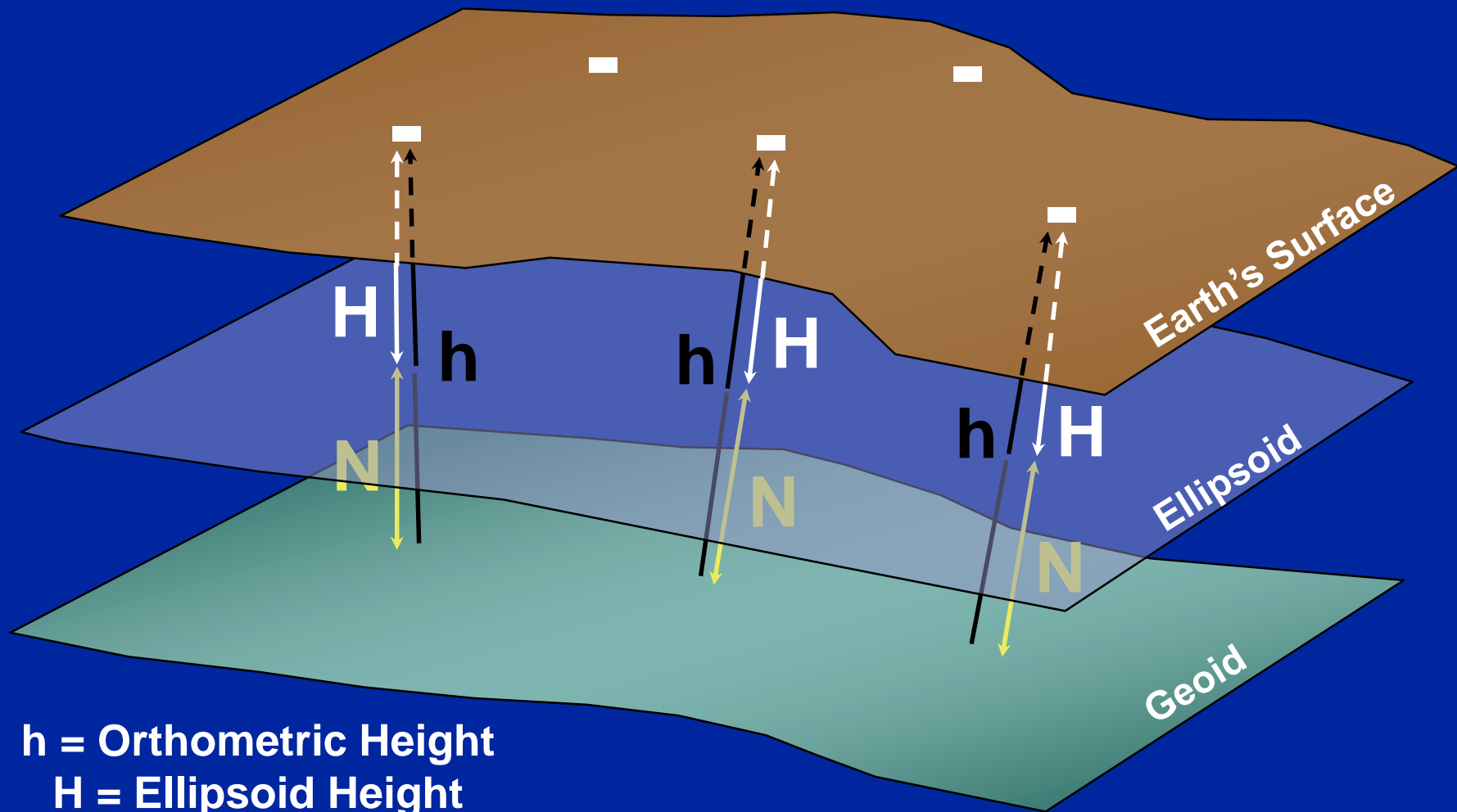
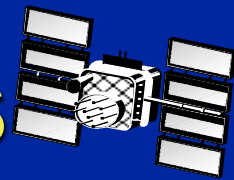
$X = -2691542.5437$ m
 $Y = -4301026.4260$ m
 $Z = 3851926.3688$ m

WGS-84

$\phi = 37^\circ 23' 26.38035''$ N
 $\lambda = 122^\circ 02' 16.62574''$ W
 $H = -5.4083$ m

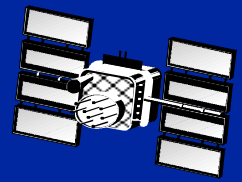


GPS Heights vs. Elevations



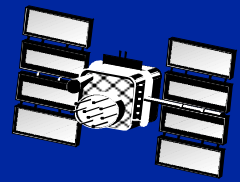
h = Orthometric Height
H = Ellipsoid Height
N = Geoid Height

$$h = H - N$$



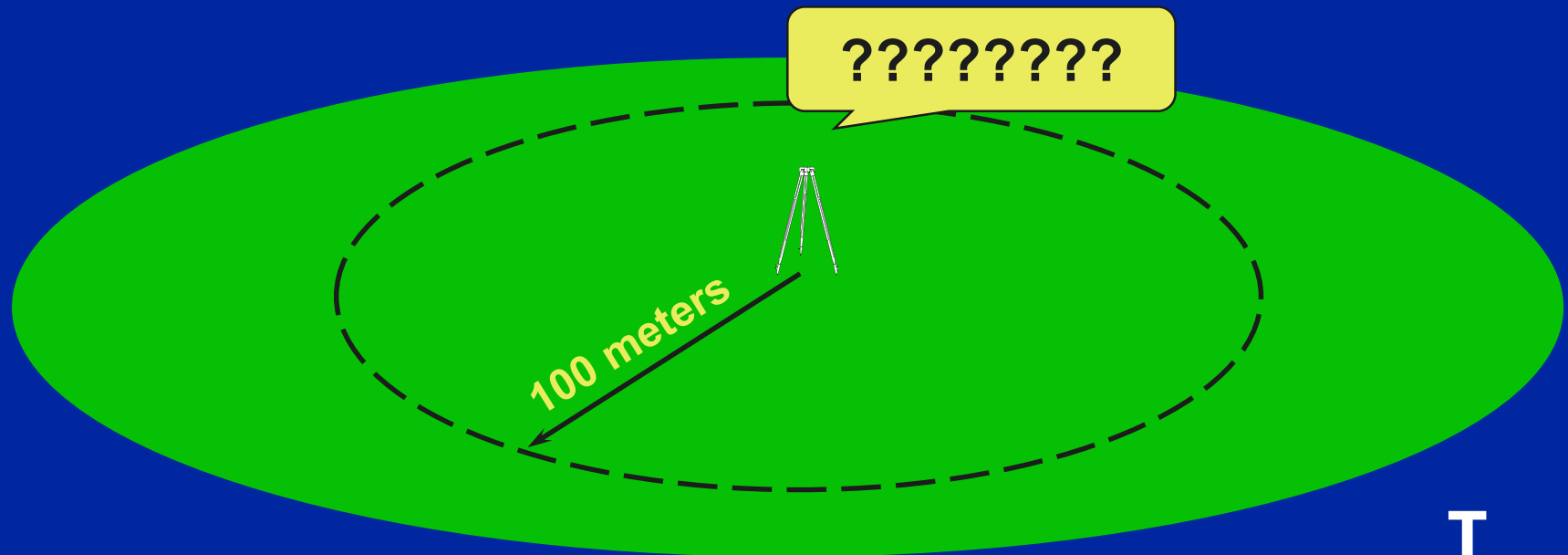
Errors Sources in GPS

- **Selective Availability (SA) and Anti-Spoofing (AS)**
- **Multipath**
- **Ionospheric Noise**
- **Human Error**

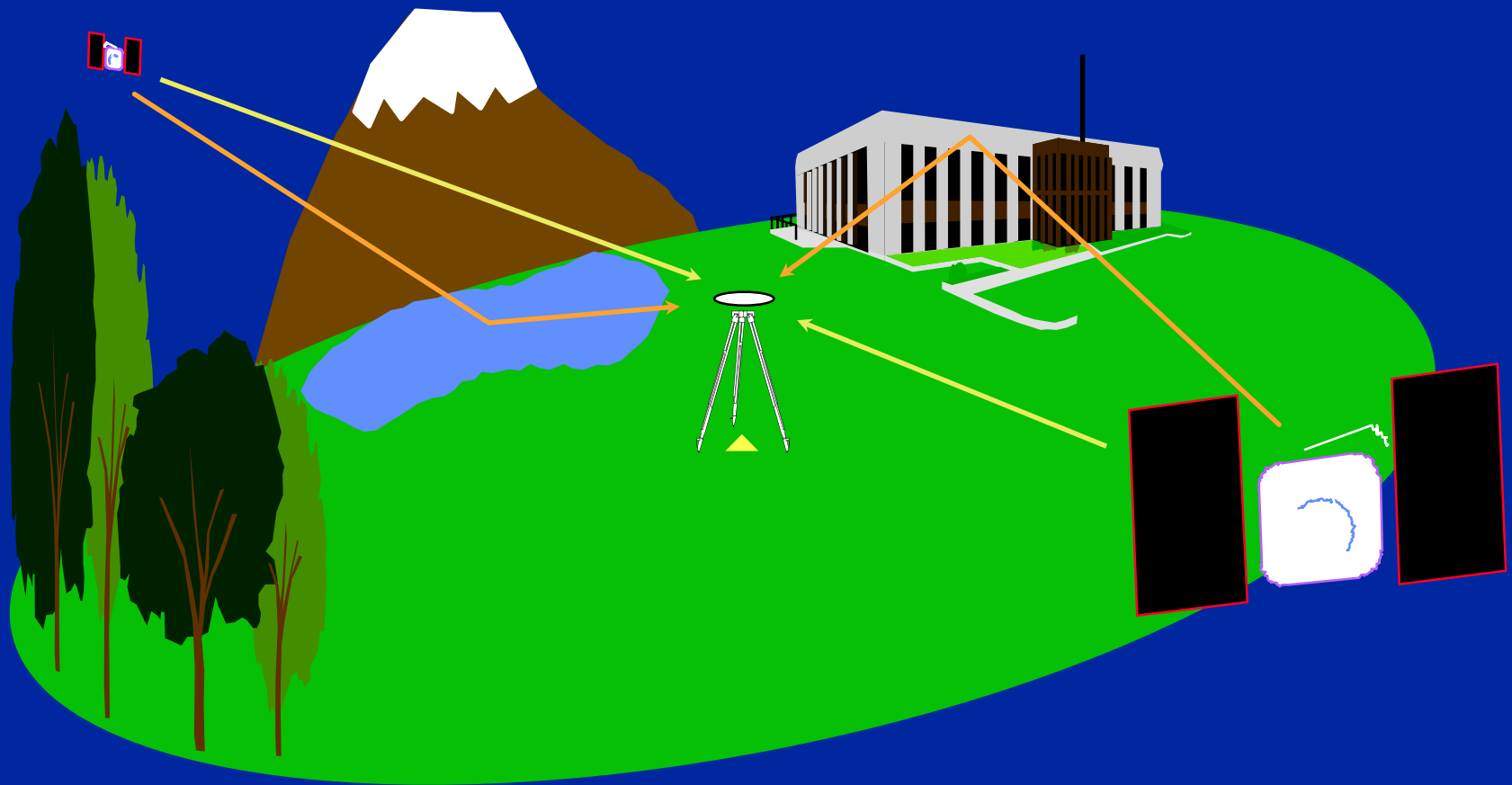
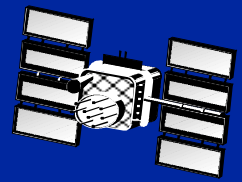


SA and AS

- Selective Availability (SA)
 - Clock dither
 - Ephemeris error
- Anti-Spoofing (AS)
 - Encryption of the P-code signal

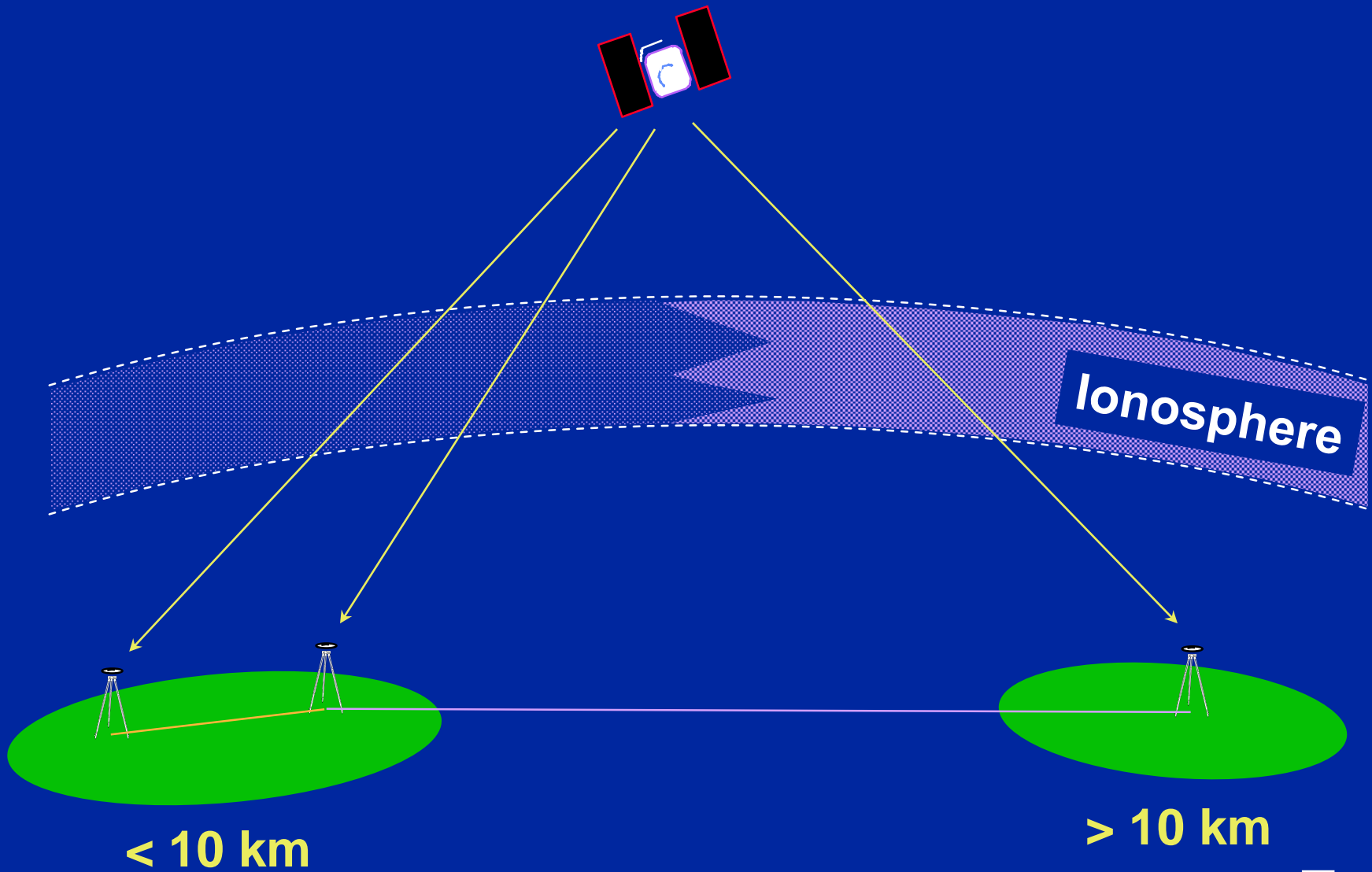
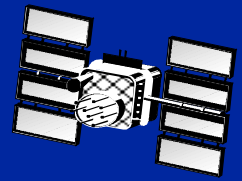


Multipath



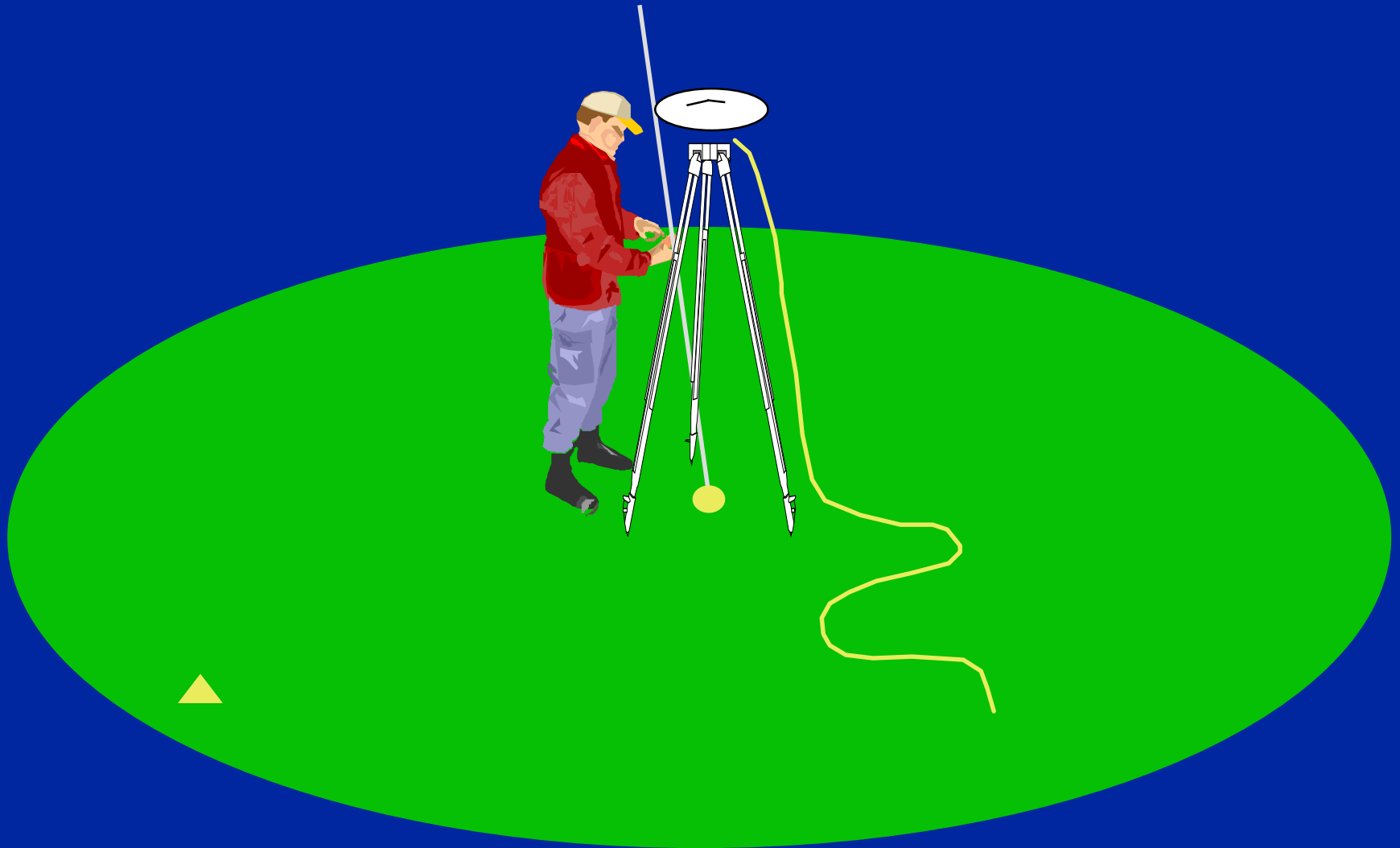
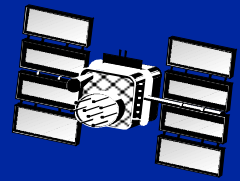
T

Ionospheric Effects

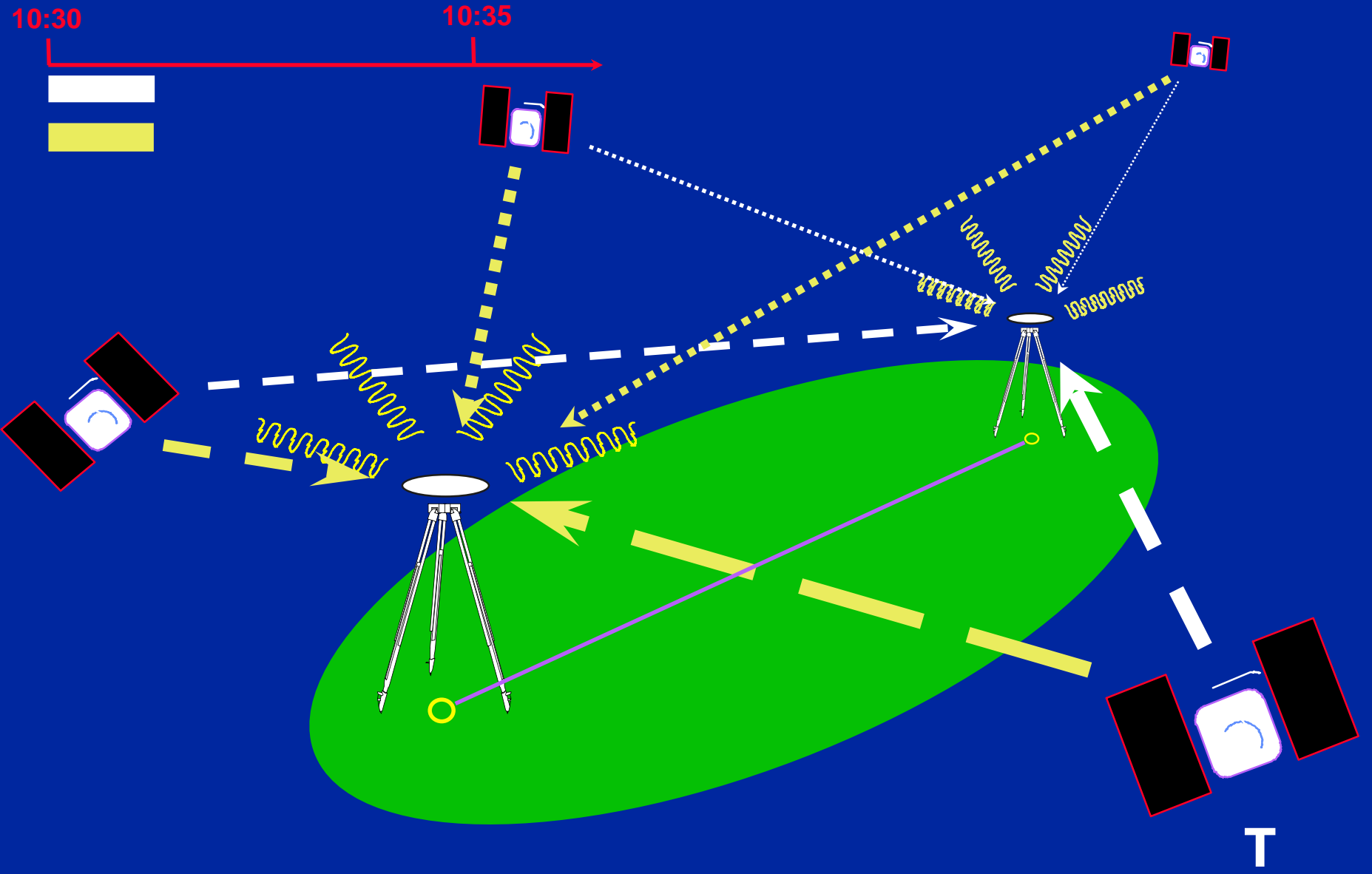
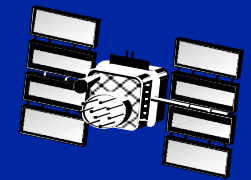


T

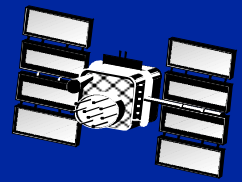
Human Error



Survey Requirements

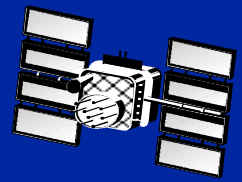


T



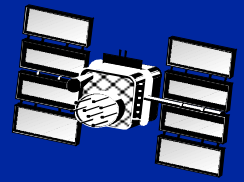
Summary

- There are three segments to GPS. All must be working to use GPS.
- There are 2 GPS signals, L1 and L2.
- Code Range measurements result in autonomous positions with several meter precision.
- Carrier Phase measurements result in relative positions with centimeter precision.



Summary (cont.)

- GPS results are in reference to an ECEF coordinate system and the WGS-84 ellipsoid.
- Errors in GPS can be minimized by planning and utilizing proper surveying techniques.
- At least 4 SVs are required to determine a position or survey with GPS.
- At least 2 receivers are required to survey with GPS.



Questions?